

Keywords: Small, High-Voltage Boost Converters

APPLICATION NOTE 1109

Small, High-Voltage Boost Converters

The biasing of avalanche photodiodes (APDs), piezoelectric transducers (PZTs), vacuum fluorescent displays (VFDs), and microelectromechanical systems (MEMS) require high-voltage power supplies. This app note presents three topologies (**Figures 1a**, **1b**, and **1c**) for generating a high output voltage from a low input voltage. The advantages and disadvantages of each are discussed with focus given to power density and circuit size. The end of the app note presents experimental data to contrast transformer-based and inductor-based solutions.



Figure 1a-1c. These high-voltage DC-DC converters in three topologies are used to create high output voltage from low input voltage.

The high-voltage bias required in many APD applications (75V) is derived from a 3V supply. That requirement presents the following challenges:

- High-voltage MOSFETs generally do not operate with a low 3V gate drive.
- The larger drain-source capacitance of high-voltage MOSFETs requires energy in the inductor to slew the drain to the output voltage. The resulting losses are as large as 1/2 f_{switch}
 ^s C_{DS}V_{OUT} ².
- High-voltage MOSFETs are larger and more expensive than their lower voltage counterparts. High-voltage power MOSFETs are seldom found within switching-controller ICs.
- Extreme duty cycles impose inefficiently small off-times or low switching frequencies. Lower switching frequency causes higher ripple and requires larger magnetics.

The circuit of Figure 1c solves these challenges by using an autotransformer. The peak voltage on the MOSFET is reduced, allowing the use of the MAX1605, which has a 28V internal MOSFET. The complete layout (smaller than an 8-pin DIP) fits on a 6mm x 8.5mm double-sided board (**Figure 2**).



Figure 2. This 6mm x 8.5mm DC-DC converter converts 2.5V to 75V using the MAX1605. The front and back layout of the circuit is shown.

Theory of Operation

Standard boost and flyback DC-DC converters can be merged to form the hybrid topology of Figure 1c. The resulting merged topology stacks secondary-winding flyback voltage on top of the input voltage and the primarywinding flyback voltage (a standard flyback converter only takes advantage of flyback voltage produced at the secondary side). Compared with a standard boost converter, this topology produces higher output voltages from a lower voltage MOSFET by limiting the voltage seen at LX.

A transformer provides the following advantages:

- Higher attainable output voltage
- Lower operating duty cycle
- Lower voltage on the MOSFET

The following advantages also accrue when operating the transformer in discontinuous mode, with a constant peak current in the MOSFET:

- Higher switching frequency produces lower output ripple
- Higher frequency ripple
- Smaller magnetics

The MAX1605 and many other boost converters can be used in this topology. Maximum output voltage is limited by the transformer turns ratio, the transformer and diode voltage ratings, the MOSFET's voltage rating and drain capacitance, and the diode's reverse-recovery time.

Standard Boost

The standard boost converter is shown in Figure 1a. When the MOSFET turns on, the inductor current ramps up. When the MOSFET turns off, LX flies up to $V_{OUT} + V_D$, and the inductor current ramps down. Intuitively, if the inductor spends 1/nth of its time delivering energy to the output, the output voltage (V_{OUT}) is n times the input voltage (V_{IN}), thus the following equation can be generated:

$$\frac{V_{OUT}}{V_{IN}} = \frac{1}{1 - D}$$

where D is the duty cycle. A more analytical proof can be found by using **Figure 3**. The key to this proof lies in steady-state operation, for which the current must ramp down the same amount that it ramps up:

$$\Delta I_{UP} = \Delta I_{DOWN}$$



Figure 3. This analysis of the inductor current for the circuit of Figure 1a can be used to determine its duty cycle.

Thus, the final inductor current equals the initial inductor current:

$$\Delta I_{UP} = \frac{V_{IN}}{L_{BST}} t_{ON} = \frac{V_{IN}}{L_{BST}} D \cdot T$$

$$\Delta I_{DOWN} = \frac{V_{OUT} - V_{IN}}{L_{BST}} t_{OFF} = \frac{V_{OUT} - V_{IN}}{L_{BST}} (1 - D) \cdot T$$

Because they are equal,

$$\frac{V_{IN}}{L_{BST}} \mathbf{D} \bullet \mathbf{T} = \frac{V_{OUT} - V_{IN}}{L_{BST}} (1 - \mathbf{D}) \bullet \mathbf{T}$$

$$V_{IN} \bullet \mathbf{D} = V_{OUT} - V_{IN} \bullet (1 - \mathbf{D})$$

$$\frac{V_{OUT}}{V_{IN}} = \frac{1}{(1 - \mathbf{D})} \quad \text{and} \quad \mathbf{D} = 1 - \frac{V_{IN}}{V_{OUT}}$$

The circuit of Figure 1b could be made equivalent to the circuit of Figure 1a by connecting the left side of the

transformer's secondary winding to V_{IN} and setting the turns ratio to 1. The secondary-side diode can be reflected to the primary side, making the relationship between a flyback converter and a boost converter easier to perceive.

Turns ratios larger than 1:1 provide leverage by allowing higher output voltage with less extreme duty cycles. Alternatively, node 1 of the transformer can be connected to any power supply, enabling leverage with respect to that supply. Because LX flies up during the off-cycle, an additional voltage step can be obtained by connecting node 1 to LX, as shown in Figure 1c. That connection also helps catch some of the leakage energy that would otherwise be dumped from the transformer's primary side to the MOSFET, producing short, high-voltage spikes at the MOSFET's drain. If the voltage spikes are higher than the MOSFET's voltage tolerance, a snubber circuit will be necessary to dissipate the leakage energy.

LX is shorted to ground in Figure 1b, allowing the primary-side current to ramp up as for an inductor. No current flows through the secondary side of the transformer and the diode is reverse-biased because

 $V_{PRIMARY} = -V_{IN}$ $V_{SECONDARY} = N_S/N_P \cdot V_{PRIMARY}.$

Primary-side current must cease when the switch at LX turns off, but the N I product must remain constant:

$$I_{P \text{ initial}} \bullet N_{P} + I_{S \text{ final}} \bullet N_{S} = I_{P \text{ initial}} \bullet N_{P} + I_{S \text{ final}} \bullet N_{S}$$

where subscript "P" indicates primary side, subscript "S" indicates secondary side, "initial" indicates current at the moment before the MOSFET is switched off, and "final" indicates current at the moment after the MOSFET is switched off.

Because $I_{S_{initial}} = I_{P_{final}} = 0$,

$$I_{S_{final}} = \frac{N_P}{N_S} I_{P_{initial}}$$

The circuit of Figure 1c is similar, except that $I_{P_{final}} = I_{S_{final}}$, so

$$I_{S_{final}} = \frac{N_{P}}{N_{P} + N_{S}} I_{P_{initial}}$$

To simplify, the turns ratio 'N' is expressed as:

$$N = \frac{N_P + N_S}{N_P}$$

because the secondary side of Figure 1c never acts independently. Though unconventional, this definition for N is more appropriate for Figure 1c.

Figure 4 shows the primary-side current waveform for Figure 1c. For step-up converters whose output is more

than twice the input voltage, off-time has a greater effect on the efficiency than on-time. Assume (for a comparable boost converter) that off-time has been minimized by minimizing inductance (L_{BST}), which also

minimizes component size to the point that further reduction would lead to undesired efficiency loss. Then, select the Figure 4 transformer's total inductance to be N times as large. Because the primary-side current ramps down from I_{PK}/N instead of I_{PK} , the primary inductance must be N times as large to maintain the same off-time.



Figure 4. This analysis of the primary-side transformer current for the circuit of Figure 1c can be used to determine its duty cycle.

The primary-side inductance is:

$$L_P = \frac{L_{TOT}}{N_2}$$

where L_{TOT} is the total inductance of the autotransformer since L_{BST} is N² smaller than L_{TOT} , and L_{TOT} is N times larger than L_{BST} , L_P is L_{BST}/N . As a result, the primary side ramps faster than a simple boost converter.

$$\begin{split} \mathbf{I}_{\text{SAT}} &= \mathbf{I}_{\text{PK}} \ / \ \mathbf{N} \\ \mathbf{L}_{\text{TOT}} &= \mathbf{L}_{\text{BST}} \bullet \mathbf{N} \\ \mathbf{LP} &= \mathbf{L}_{\text{TOT}} \ / \ \mathbf{N}^2 = \mathbf{L}_{\text{BST}} \ / \ \mathbf{N} \end{split}$$

For the steady state, it is clear from Figure 4 that:

$$\Delta I_{UP} = I_{PK}$$
 and $\Delta I_{DOWN} = \frac{I_{PK}}{N} = \frac{\Delta I_{UP}}{N}$

where ΔI_{UP} is the upward step in the primary-side current and ΔI_{DOWN} is the downward step. ΔI_{UP} and ΔI_{DOWN} can be calculated as follows:

$$\Delta I_{UP} = \frac{V_{IN}}{L_P} t_{ON} = \frac{V_{IN}}{L_{BST}/N} \mathbf{D} \cdot \mathbf{T}$$

and

$$\Delta I_{\text{DOWN}} = \frac{V_{\text{OUT}} - V_{\text{IN}}}{L_{\text{TOT}}} t_{\text{OFF}} = \frac{V_{\text{OUT}} - V_{\text{IN}}}{L_{\text{BST}} \cdot N} (1 - D) \cdot T$$

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$$\frac{V_{OUT} - V_{IN}}{L_{BST} \bullet N} (1 - D) \bullet T = \frac{V_{IN}}{L_{BST} \bullet N/N} D \bullet T$$

Solving for V_{OUT}/V_{IN} yields:

$$\frac{V_{OUT}}{V_{IN}} = \frac{N \cdot D}{1 - D} + 1 \quad \text{and} \quad D = \frac{V_{OUT} - V_{IN}}{V_{IN}(N - 1) + V_{OUT}}$$

Figures 3 and 4 are both drawn to scale and have the same off-time (set to some optimal minimum). The shaded regions in Figures 3 and 4 represent energy delivered to the load, and the energy per pulse is proportional to the area of those regions. That energy can also be calculated from the expression 1/2 L • I² (note that L in Figure 4 is N times larger, and I is N times smaller). Because the circuit of Figure 1c delivers less energy per pulse, the ripple is N times smaller. Thus, a transformer not only leverages the output voltage up; it also leverages the output ripple down.

The topology of Figure 1c delivers less energy per pulse, but compensates by delivering more pulses, as clearly indicated in Figure 4. Figure 1c requires an N times larger inductance, but the saturation current can be N times smaller because the primary and secondary side see only I_{PK}/N as much current simultaneously. With an I_{SAT}

smaller by a factor of N and an inductance N times larger, the transformer's energy-storage capability may also be N times smaller. Transformer size is a function of its energy-storage capability, so in theory you can use a transformer that is physically smaller by a factor of N. In practice, the attainable size is determined by market limitations.

Output Ripple

For discontinuous conduction, either converter's output ripple can be calculated by equating energy change in the inductor or transformer with energy change in the output capacitor during the off-cycle. Because the inductor/transformer has zero energy at the end of the cycle, no-load ripple can be calculated as:

$$\begin{split} &\frac{1}{2} \operatorname{LI}^2 = \frac{1}{2} \operatorname{C}_{\operatorname{OUT}} \operatorname{V}_{\operatorname{final}}^2 - \frac{1}{2} \operatorname{C}_{\operatorname{OUT}} \operatorname{V}_{\operatorname{initial}}^2 \\ &\frac{1}{2} \operatorname{LI}^2 = \frac{1}{2} \operatorname{C}_{\operatorname{OUT}} (\operatorname{V}_{\operatorname{final}} - \operatorname{V}_{\operatorname{initial}}) \bullet (\operatorname{V}_{\operatorname{final}} + \operatorname{V}_{\operatorname{initial}}) \\ &\frac{1}{2} \operatorname{LI}^2 = \operatorname{C}_{\operatorname{OUT}} \Delta \operatorname{V}_{\operatorname{OUT}} \bullet \operatorname{V}_{\operatorname{OUT}} \\ &\Delta \operatorname{V}_{\operatorname{OUT}} = \frac{\frac{1}{2} \operatorname{LI}^2}{\operatorname{C}_{\operatorname{OUT}} \operatorname{V}_{\operatorname{OUT}}} \end{split}$$

For the boost converter L = L_{BST} and I = I_{PK}. For the circuit of Figure 1c, L = L_{BST} \blacksquare N and I = I_{PK}/N, so:

$$\Delta V_{OUTA} = \frac{\frac{1}{2} L_{BST} (I_{PK})^2}{CV_{OUT}}$$
$$\Delta V_{OUTC} = \frac{\frac{1}{2} N \cdot L_{BST} \left(\frac{I_{PK}}{N}\right)^2}{CV_{OUT}} = \frac{\Delta V_{OUTA}}{N}$$

where ΔV_{OUTA} is the output ripple of the boost configuration, and ΔV_{OUTC} is the output ripple for the Figure 1c circuit. Ripple in Figure 1c is 1/Nth as large for the boost configuration and the switching frequency is N times higher.

Figure 5 offers a comparison of ripple for the circuits of Figures 1a and 1c, when both circuits are designed for the same off-time. Because the duty cycle is normalized in the transformer circuit (made closer to 50%), the controller can operate at a frequency N times higher for the same off-time.



Figure 5. This illustration contrasts the ripple produced by the circuit of Figure 1a vs. the circuit of Figure 1c assuming both are optimized for a minimum acceptable off-time.

Efficiency Considerations

There are three main efficiency losses to consider in the transformer topology. Transformer/inductor DC resistance combined with switch resistance produces losses proportional to the square of the peak current. Transformer-leakage inductance produces loss because transformer energy is not completely coupled to the output. When the diode is quickly and heavily reverse-biased (when the MOSFET turns on), any delay in the diode (the reverse-recovery time, t_{RR}) can also cause significant loss.

The percent efficiency loss due to DC resistance in the switch and in the primary side of the transformer is independent of load, and can be approximated as:

$$\frac{E_{R_LOSS}}{E_{R_LOSS} + E_{delivered}} \cdot 100\%$$

where E_{R_LOSS} is the energy loss due to resistance per pulse, and $E_{delivered}$ is the energy delivered per pulse. By taking the integral of the primary-side resistive power dissipation, the resistive efficiency loss for large duty cycles can be approximated as:

$$\frac{\frac{1}{3}I_{PK}R}{\frac{1}{3}I_{PK}R + \frac{1}{2}V_{IN}} \cdot 100\%$$

where D is the duty cycle expressed as a percentage, and R is the sum of the switch resistance and the primaryside resistance. For operation in discontinuous mode, the same equation applies for the circuit of Figure 1a or 1c. The efficiency loss due to leakage inductance can be approximated as:

$$\frac{L_{Leakage}}{L_{Leakage} + L_{Primary}} \cdot 100\%$$

where L_{leakage} is the total leakage inductance seen at the primary side. Transformers with higher turns ratios provide larger leakage inductance, higher frequency, and deliver lower energy per pulse, so the source of inefficiency becomes more significant.

Transformer Selection

Since the selection of off-the-shelf transformers is much narrower than that of equivalent inductors, transformers generally cost more than inductors of equivalent energy and energy density. The customer base for transformers is smaller, yet the set of possible transformer configurations is much larger than that of corresponding inductor configurations. As a result, magnetic designs based on custom transformers are often necessary.

When specifying an autotransformer, consider an equivalent inductor. The following inductor, for example, is available from Toko:

D32FU 680 μH, 74mA, 20Ω, 3.5mm 🛚 3.5mm 🖷 2.2mm.

It is reasonable to ask for an autotransformer whose end-to-end characteristics are similar. For such a transformer with a 1:9 turns ratio, the primary-side rating would be 6.8 μ H, 740mA, and 2 Ω . That inductance rating is based on a value of N² (where N is the total number of turns divided by the number of primary-side turns). For a 1:9 turns ratio there must be some multiple of 10 turns total. N = 10 must be used for the previous calculation. The saturation current is inversely proportional to N and resistance is proportional to N.

Occasionally, thermal limitations do not allow the maximum current rating to scale by N. Also, a limited product selection may bar you from that ideal starting point. This analysis provides a starting point and a decent edge when discussing possibilities with a custom transformer vendor. When wound as an autotransformer, an equivalent magnetic component should require less space (a smaller wiring cavity) because the lower currents

allow thinner wire on the secondary side. Extra manufacturing costs usually prohibit this approach, however.

Application

The circuit of **Figure 6** produces an APD bias of 75V. Because the transformer reduces voltage stress on the switch, you can use a small 6-pin SOT23 device such as the MAX1605. The 28V, 500mA MOSFET in that IC is more than adequate since it only sees peak voltages of $V_{IN} + (V_{OUT} - V_{IN})/N = 17V$. With a higher turns ratio, the circuit can handle higher voltages.



Figure 6. This circuit, whose layout is shown in Figure 2, is used to produce 75V from 2.5V.

Figure 7 shows the MAX1605 maximum output current (the measured typical, for which the controller falls out of regulation by 5%) as a function of output voltage and input voltage.



Figure 7. This maximum load vs. output voltage graph illustrates the maximum load deliverable by the circuit of Figure 6.

Output ripple for the circuit of Figure 1c can be calculated as:

$$V_{RIPPLE} = \frac{\frac{1}{2}L_P \cdot I_{PK}^2}{C_{OUT} \cdot V_{OUT}}$$

where L_P is the primary-side inductance, I_{PK} is the peak primary-side current (500mA), C_{OUT} is the output capacitance (0.47µF), and V_{OUT} is the output voltage. For a 75V output, the ripple is 16mV_{P-P}. The low inductance that produces such a low ripple is typically not efficient in a straight boost configuration like Figure 1a.

Even $16mV_{P-P}$ ripple is not small enough for many applications. To bias an APD, high ripple is unacceptable because it couples directly into the signal. Such applications can use an RC or LC filter following the power supply, but the resistor in an RC filter produces a load-regulation error. Typical load currents are small, but the ripple filter may require large resistors.

At 100V, high-capacitance values require board space, so the filter is composed largely of resistance. For the same cutoff frequency (using the same resistor and capacitor), you can reduce the load-regulation error by a factor of β using the circuit of **Figure 8**. Although a fixed V_{BE} drop is introduced instead, that approach dramatically reduces the dependence of V_{OUT} on load. To achieve greater ripple reduction for the same level of load regulation, a β -times larger filter resistor can be used.



Figure 8. A filter further reduces ripple.

Experimental Comparison, Inductor and Transformer Approaches

For a fair comparison of inductors versus transformers in a high-voltage converter, a switching converter with the following features was selected:

- External MOSFETs
- Adjustable switching frequency
- Adjustable current limitEvaluation kit available

The MAX668 current-mode controller fulfills these criteria while eliminating the need for a feedforward capacitor. The circuit of **Figure 9** allows you to compare performance by swapping the transformer for an inductor and by swapping MOSFETs.



Figure 9. This circuit can be used to deliver higher power and higher output voltage.

The MAX668 includes a MOSFET driver that can efficiently drive the 48nC gate charge of an IRF7401 MOSFET. With the following components, it forms a 150V inductor-based boost converter. The following components were used in conjunction with the MAX668 Evaluation Kit:

- Inductor: Coilcraft DO1813P-472HC 4.7µH, 2.6A 0.054Ω inductor<
- Ultra-fast diode: ES1D 200V 15ns reverse-recovery time
- MOSFET: IRF640NS 200V 0.15 Ω Q_G = 67nC, C_{OSS} = 185pF, and provides over 2A with 5.5V gate drive
- Sense resistor: 50m Ω sense resistor

Another resistor connected between the FB terminal and a voltage source allows that source to adjust the output voltage by sinking or sourcing current to the FB terminal. You can then adjust the output voltage to 150V and the input voltage to 6V.

For the inductor-based solution, the maximum load current is 18mA at 150V (2.7W). Peak efficiency (65%) occurs at maximum load and the quiescent (no-load) current is 91mA with a 6V supply. The quiescent-current loss in the inductor circuit is due to the diode's reverse-recovery time and the MOSFET's drain capacitance. Those effects are illustrated in **Figure 10**.



Figure 10. This scope photo (left) demonstrates the effect of the ES1D diode's 15ns reverse-recovery time. The zoom of the waveform (right) reveals that the inductor current actually ramps negative since the diode fails to turn off in time.

The transformer-based approach (**Figure 11**) was implemented by exchanging the inductor for the following transformer, using the topology of Figure 1c:

 $\begin{array}{l} \mbox{Sumida CMD-8LN 6313-T036,} \\ \mbox{L}_{P} = 5.6 \mu H, \mbox{I}_{P} = 2.3 A, \mbox{N}_{P} : \mbox{NS} = 1 : 9, \\ \mbox{R}_{P} = 0.5 \Omega \end{array}$



Figure 11. The switching waveform shows the transformer-based approach for the MAX668 circuit, a 150V stepup DC-DC converter shown in Figure 9.

Using a transformer with a 1:9 turns ratio requires only a 22V MOSFET, but an actual application would use a 30V MOSFET (instead of a 200V MOSFET) for the transformer circuit. Yet, the efficiency is 77% while delivering 25.5mA at 150V (3.8W). Peak efficiency is 88% at 15mA, and the no-load supply current is only 1.8mA total.

Using the 200V MOSFET with a transformer allows the possibility of much higher voltage. A 200V MOSFET and 1:9 transformer can approach output voltages as high as 2kV in theory, but in practice the transformer windings cannot sustain such high voltage. A greater problem, however, is obtaining >1kV diodes with fast reverse-recovery times. For slow reverse-recovery times, the switching speed must be reduced.

Substituting a 400V CMR1U-04 diode from Central Semiconductor (50ns t_{RR}) for the ES1D diode and changing the output capacitors allows the circuit to produce outputs as high as 400V. The ES1D diode cannot reliably produce outputs greater than 346V, because its anode goes to -9 \bullet V_{IN} when the MOSFET turns on. Configured for V_{OUT} = 330V, the circuit was able to produce 9.6mA (3.1W) at 60% efficiency and the peak efficiency was 66% at 4mA.

As mentioned earlier, a 30V MOSFET is more logical for the 150V output. The IRF640NS was replaced with a logic-level IRF7811W (30V, 0.012Ω , $Q_G = 18nC$, $C_{DSS} = 500pF$). Resistance drops dramatically (from 0.15Ω to 0.012Ω), but the efficiency improvement is minor. When delivering a maximum load of 25.7mA at 150V, the efficiency is 82.3% (vs.77%). Peak efficiency at 15.5mA is 88%. Efficiency results are summarized in **Figure 12**.



Figure 12. This efficiency vs. load graph compares and contrasts transformer-based, step-up DC-DC converters vs. inductor-based, step-up DC-DC converters. The maximum load, quiescent current, and efficiency are greatly improved using a transformer.

The insignificant improvement in efficiency implies two things. Primary losses are in the transformer (resistive loss and leakage energy), and capacitive losses are in the MOSFET. The dominant loss is associated with the transformer's primary-side resistance, which is about 0.5Ω . You can scale this system to provide higher power. For example, another custom transformer specified for $I_{PSAT} = 5A$ and $L_P = 1.7 \mu$ H should deliver more than twice as much power.

Thus, besides use of the smaller, cheaper, and more efficient IRF7811W MOSFET, a transformer boost converter can operate with lower input voltages. Transformer leverage can improve power density and efficiency, reduce

ripple, and allow the use of smaller, cheaper, and sometimes internal MOSFETS. The cost of applying transformer leverage is mostly due to market limitations. When size and power density are a high priority, consider using transformers.

Application Note 1109: <u>http://www.maxim-ic.com/an1109</u>

More Information

For technical questions and support: <u>http://www.maxim-ic.com/support</u> For samples: <u>http://www.maxim-ic.com/samples</u> Other questions and comments: <u>http://www.maxim-ic.com/contact</u>

Related Parts

MAX1605: <u>QuickView</u> -- <u>Full (PDF) Data Sheet</u> -- <u>Free Samples</u> MAX668: <u>QuickView</u> -- <u>Full (PDF) Data Sheet</u> -- <u>Free Samples</u>

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